

Nonlinear Diffusion. Porous Medium and Fast Diffusion. From Analysis to Physics and Geometry

Juan Luis Vázquez

Departamento de Matemáticas
Universidad Autónoma de Madrid

♠ *LMS-EPSRC Summer Course*

Swansea, July 2008 ♠

Introduction

- Main topic after 1981: Nonlinear Diffusion

Introduction

- Main topic after 1981: Nonlinear Diffusion
- Particular topics: Porous Medium and Fast Diffusion flows

Introduction

- Main topic after 1981: Nonlinear Diffusion
- Particular topics: Porous Medium and Fast Diffusion flows
- Aim: to develop a complete mathematical theory with sound physical basis

The resulting theory involves PDEs, Functional Analysis, Inf. Dim. Dyn. Systems; Diff. Geometry and Probability

Introduction

- Main topic after 1981: Nonlinear Diffusion
- Particular topics: Porous Medium and Fast Diffusion flows
- Aim: to develop a complete mathematical theory with sound physical basis

The resulting theory involves PDEs, Functional Analysis, Inf. Dim. Dyn. Systems; Diff. Geometry and Probability

- H. Brezis, Ph. Bénilan
D. G. Aronson, L. A. Caffarelli
L. A. Peletier, S. Kamin, G. Barenblatt, V. A. Galaktionov

Introduction

- Main topic after 1981: Nonlinear Diffusion
- Particular topics: Porous Medium and Fast Diffusion flows
- Aim: to develop a complete mathematical theory with sound physical basis

The resulting theory involves PDEs, Functional Analysis, Inf. Dim. Dyn. Systems; Diff. Geometry and Probability

- H. Brezis, Ph. Bénilan
D. G. Aronson, L. A. Caffarelli
L. A. Peletier, S. Kamin, G. Barenblatt, V. A. Galaktionov
+ M. Crandall, L. Evans, A. Friedman, C. Kenig,...

I. Diffusion

Populations diffuse, substances (like particles in a solvent) diffuse, heat propagates, electrons and ions diffuse, the momentum of a viscous (Newtonian) fluid diffuses (linearly), there is diffusion in the markets, ...

- *what is diffusion anyway?*
- *how to explain it with mathematics?*
- *A main question is: how much of it can be explained with **linear models**, how much is **essentially nonlinear**?*
- *The stationary states of diffusion belong to an important world, **elliptic equations**. Elliptic equations, linear and nonlinear, have many relatives: *diffusion, fluid mechanics, waves of all types, quantum mechanics, ...**

The heat equation origins

- We begin our presentation with the Heat Equation $u_t = \Delta u$ and the analysis proposed by Fourier, 1807, 1822 (Fourier decomposition, spectrum). The mathematical models of heat propagation and diffusion have made great progress both in theory and application. They have had a strong influence on the 5 areas of Mathematics already mentioned.

The heat equation origins

- We begin our presentation with the Heat Equation $u_t = \Delta u$ and the analysis proposed by Fourier, 1807, 1822 (Fourier decomposition, spectrum). The mathematical models of heat propagation and diffusion have made great progress both in theory and application. They have had a strong influence on the 5 areas of Mathematics already mentioned.
- The heat flow analysis is based on two main techniques: integral representation (convolution with a Gaussian kernel) and mode separation:

$$u(x, t) = \sum T_i(t) X_i(x)$$

where the $X_i(x)$ form the spectral sequence

$$-\Delta X_i = \lambda_i X_i.$$

This is the famous linear eigenvalue problem

Linear heat flows

- From 1822 until 1950 the heat equation has motivated
 - (i) Fourier analysis decomposition of functions (and set theory),
 - (ii) development of other linear equations
- ⇒ Theory of Parabolic Equations

$$u_t = \sum a_{ij} \partial_i \partial_j u + \sum b_i \partial_i u + cu + f$$

Linear heat flows

- From 1822 until 1950 the heat equation has motivated
 - (i) Fourier analysis decomposition of functions (and set theory),
 - (ii) development of other linear equations \implies Theory of Parabolic Equations

$$u_t = \sum a_{ij} \partial_i \partial_j u + \sum b_i \partial_i u + cu + f$$

- Main inventions in **Parabolic Theory**:
 - (1) a_{ij}, b_i, c, f **regular** \implies Maximum Principles, Schauder estimates, Harnack inequalities; C^α spaces (Hölder); potential theory; generation of semigroups.
 - (2) **coefficients only continuous or bounded** \implies $W^{2,p}$ estimates, Calderón-Zygmund theory, weak solutions; Sobolev spaces.

Linear heat flows

- From 1822 until 1950 the heat equation has motivated
 - (i) Fourier analysis decomposition of functions (and set theory),
 - (ii) development of other linear equations \implies Theory of Parabolic Equations

$$u_t = \sum a_{ij} \partial_i \partial_j u + \sum b_i \partial_i u + cu + f$$

- Main inventions in **Parabolic Theory**:
 - a_{ij}, b_i, c, f **regular** \implies Maximum Principles, Schauder estimates, Harnack inequalities; C^α spaces (Hölder); potential theory; generation of semigroups.
 - coefficients only continuous or bounded** \implies $W^{2,p}$ estimates, Calderón-Zygmund theory, weak solutions; Sobolev spaces.
- The probabilistic approach**: Diffusion as an stochastic process: Bachelier, Einstein, Smoluchowski, Wiener, Levy, Ito,...

$$dX = bdt + \sigma dW$$

Nonlinear heat flows

- In the last 50 years emphasis has shifted towards the **Nonlinear World**. Maths more difficult, more complex and more realistic. My group works in the areas of **Nonlinear Diffusion** and **Reaction Diffusion**.

I will present an overview and recent results in the theory mathematically called **Nonlinear Parabolic PDEs**. General formula

$$u_t = \sum \partial_i A_i(u, \nabla u) + \sum B(x, u, \nabla u)$$

Nonlinear heat flows

- In the last 50 years emphasis has shifted towards the **Nonlinear World**. Maths more difficult, more complex and more realistic. My group works in the areas of **Nonlinear Diffusion** and **Reaction Diffusion**.

I will present an overview and recent results in the theory mathematically called **Nonlinear Parabolic PDEs**. General formula

$$u_t = \sum \partial_i A_i(u, \nabla u) + \sum B(x, u, \nabla u)$$

- Typical nonlinear diffusion: $u_t = \Delta u^m$

Typical reaction diffusion: $u_t = \Delta u + u^p$

The Nonlinear Diffusion Models

- The Stefan Problem (Lamé and Clapeyron, 1833; Stefan 1880)

$$SE : \begin{cases} u_t = k_1 \Delta u & \text{for } u > 0, \\ u_t = k_2 \Delta u & \text{for } u < 0. \end{cases} \quad TC : \begin{cases} u = 0, \\ \mathbf{v} = L(k_1 \nabla u_1 - k_2 \nabla u_2). \end{cases}$$

Main feature: the **free boundary** or **moving boundary** where $u = 0$. TC= Transmission conditions at $u = 0$.

The Nonlinear Diffusion Models

- The Stefan Problem (Lamé and Clapeyron, 1833; Stefan 1880)

$$SE : \begin{cases} u_t = k_1 \Delta u & \text{for } u > 0, \\ u_t = k_2 \Delta u & \text{for } u < 0. \end{cases} \quad TC : \begin{cases} u = 0, \\ \mathbf{v} = L(k_1 \nabla u_1 - k_2 \nabla u_2). \end{cases}$$

Main feature: the **free boundary** or **moving boundary** where $u = 0$. TC= Transmission conditions at $u = 0$.

- The Hele-Shaw cell (Hele-Shaw, 1898; Saffman-Taylor, 1958)

$$u > 0, \Delta u = 0 \quad \text{in } \Omega(t); \quad u = 0, \mathbf{v} = L \partial_n u \quad \text{on } \partial\Omega(t).$$

The Nonlinear Diffusion Models

- The Stefan Problem (Lamé and Clapeyron, 1833; Stefan 1880)

$$SE : \begin{cases} u_t = k_1 \Delta u & \text{for } u > 0, \\ u_t = k_2 \Delta u & \text{for } u < 0. \end{cases} \quad TC : \begin{cases} u = 0, \\ \mathbf{v} = L(k_1 \nabla u_1 - k_2 \nabla u_2). \end{cases}$$

Main feature: the **free boundary** or **moving boundary** where $u = 0$. TC= Transmission conditions at $u = 0$.

- The Hele-Shaw cell (Hele-Shaw, 1898; Saffman-Taylor, 1958)

$$u > 0, \Delta u = 0 \quad \text{in } \Omega(t); \quad u = 0, \mathbf{v} = L \partial_n u \quad \text{on } \partial\Omega(t).$$

- The Porous Medium Equation \rightarrow (*hidden free boundary*)

$$u_t = \Delta u^m, \quad m > 1.$$

The Nonlinear Diffusion Models

- The Stefan Problem (Lamé and Clapeyron, 1833; Stefan 1880)

$$SE : \begin{cases} u_t = k_1 \Delta u & \text{for } u > 0, \\ u_t = k_2 \Delta u & \text{for } u < 0. \end{cases} \quad TC : \begin{cases} u = 0, \\ \mathbf{v} = L(k_1 \nabla u_1 - k_2 \nabla u_2). \end{cases}$$

Main feature: the **free boundary** or **moving boundary** where $u = 0$. TC= Transmission conditions at $u = 0$.

- The Hele-Shaw cell (Hele-Shaw, 1898; Saffman-Taylor, 1958)

$$u > 0, \Delta u = 0 \quad \text{in } \Omega(t); \quad u = 0, \mathbf{v} = L \partial_n u \quad \text{on } \partial\Omega(t).$$

- The Porous Medium Equation \rightarrow (*hidden free boundary*)

$$u_t = \Delta u^m, \quad m > 1.$$

- The p -Laplacian Equation, $u_t = \operatorname{div} (|\nabla u|^{p-2} \nabla u)$.

The Reaction Diffusion Models

- The Standard Blow-Up model (Kaplan, 1963; Fujita, 1966)

$$u_t = \Delta u + u^p$$

Main feature: If $p > 1$ the norm $\|u(\cdot, t)\|_\infty$ of the solutions goes to infinity in finite time. Hint: Integrate $u_t = u^p$.

Problem: *what is the influence of diffusion / migration?*

The Reaction Diffusion Models

- The Standard Blow-Up model (Kaplan, 1963; Fujita, 1966)

$$u_t = \Delta u + u^p$$

Main feature: If $p > 1$ the norm $\|u(\cdot, t)\|_\infty$ of the solutions goes to infinity in finite time. Hint: Integrate $u_t = u^p$.

Problem: *what is the influence of diffusion / migration?*

- General scalar model

$$u_t = \mathcal{A}(u) + f(u)$$

The Reaction Diffusion Models

- The Standard Blow-Up model (Kaplan, 1963; Fujita, 1966)

$$u_t = \Delta u + u^p$$

Main feature: If $p > 1$ the norm $\|u(\cdot, t)\|_\infty$ of the solutions goes to infinity in finite time. Hint: Integrate $u_t = u^p$.

Problem: *what is the influence of diffusion / migration?*

- General scalar model

$$u_t = \mathcal{A}(u) + f(u)$$

- The system model: $\vec{u} = (u_1, \dots, u_m) \rightarrow$ chemotaxis.

The Reaction Diffusion Models

- The Standard Blow-Up model (Kaplan, 1963; Fujita, 1966)

$$u_t = \Delta u + u^p$$

Main feature: If $p > 1$ the norm $\|u(\cdot, t)\|_\infty$ of the solutions goes to infinity in finite time. Hint: Integrate $u_t = u^p$.

Problem: *what is the influence of diffusion / migration?*

- General scalar model

$$u_t = \mathcal{A}(u) + f(u)$$

- The system model: $\vec{u} = (u_1, \dots, u_m) \rightarrow$ chemotaxis.
- The fluid flow models: Navier-Stokes or Euler equation systems for incompressible flow. *Any singularities?*

The Reaction Diffusion Models

- The Standard Blow-Up model (Kaplan, 1963; Fujita, 1966)

$$u_t = \Delta u + u^p$$

Main feature: If $p > 1$ the norm $\|u(\cdot, t)\|_\infty$ of the solutions goes to infinity in finite time. Hint: Integrate $u_t = u^p$.

Problem: *what is the influence of diffusion / migration?*

- General scalar model

$$u_t = \mathcal{A}(u) + f(u)$$

- The system model: $\vec{u} = (u_1, \dots, u_m) \rightarrow$ chemotaxis.
- The fluid flow models: Navier-Stokes or Euler equation systems for incompressible flow. *Any singularities?*
- The geometrical models: the Ricci flow: $\partial_t g_{ij} = -R_{ij}$.

An opinion of John Nash, 1958:

The open problems in the area of **nonlinear p.d.e.** are very relevant to applied mathematics and science as a whole, perhaps more so than the open problems in any other area of mathematics, and the field seems poised for rapid development. It seems clear, however, that **fresh methods** must be employed...

Little is known about the **existence, uniqueness and smoothness** of solutions of the general equations of flow for a viscous, compressible, and heat conducting fluid...

*“Continuity of solutions of elliptic and parabolic equations”,
paper published in Amer. J. Math, 80, no 4 (1958), 931-954*

II. Porous Medium Diffusion

$$u_t = \Delta u^m = \nabla \cdot (c(u) \nabla u)$$

density-dependent diffusivity

$$c(u) = m u^{m-1} [= m |u|^{m-1}]$$

degenerates at $u = 0$ if $m > 1$

Applied motivation for the PME

- Flow of gas in a porous medium (Leibenzon, 1930; Muskat 1933) $m = 1 + \gamma \geq 2$

$$\begin{cases} \rho_t + \operatorname{div}(\rho \mathbf{v}) = 0, \\ \mathbf{v} = -\frac{k}{\mu} \nabla p, \quad p = p(\rho). \end{cases}$$

Second line left is the **Darcy law** for flows in porous media (Darcy, 1856). *Porous media flows are potential flows due to averaging of Navier-Stokes on the pore scales.*

To the right, put $p = p_o \rho^\gamma$, with $\gamma = 1$ (isothermal), $\gamma > 1$ (adiabatic flow).

$$\rho_t = \operatorname{div} \left(\frac{k}{\mu} \rho \nabla p \right) = \operatorname{div} \left(\frac{k}{\mu} \rho \nabla (p_o \rho^\gamma) \right) = c \Delta \rho^{\gamma+1}.$$

Applied motivation for the PME

- Flow of gas in a porous medium (Leibenzon, 1930; Muskat 1933) $m = 1 + \gamma \geq 2$

$$\begin{cases} \rho_t + \operatorname{div}(\rho \mathbf{v}) = 0, \\ \mathbf{v} = -\frac{k}{\mu} \nabla p, \quad p = p(\rho). \end{cases}$$

Second line left is the **Darcy law** for flows in porous media (Darcy, 1856). *Porous media flows are potential flows due to averaging of Navier-Stokes on the pore scales.*

To the right, put $p = p_o \rho^\gamma$, with $\gamma = 1$ (isothermal), $\gamma > 1$ (adiabatic flow).

$$\rho_t = \operatorname{div} \left(\frac{k}{\mu} \rho \nabla p \right) = \operatorname{div} \left(\frac{k}{\mu} \rho \nabla (p_o \rho^\gamma) \right) = c \Delta \rho^{\gamma+1}.$$

- Underground water infiltration (Boussinesq, 1903) $m = 2$

Applied motivation II

- Plasma radiation $m \geq 4$ (Zeldovich-Raizer, < 1950)

Experimental fact: diffusivity at high temperatures is not constant as in Fourier's law, due to radiation.

$$\frac{d}{dt} \int_{\Omega} c\rho T \, dx = \int_{\partial\Omega} k(T) \nabla T \cdot \mathbf{n} \, dS.$$

Put $k(T) = k_o T^n$, apply Gauss law and you get

$$c\rho \frac{\partial T}{\partial t} = \operatorname{div}(k(T) \nabla T) = c_1 \Delta T^{n+1}.$$

→ When k is not a power we get $T_t = \Delta \Phi(T)$ with $\Phi'(T) = k(T)$.

Applied motivation II

- Plasma radiation $m \geq 4$ (Zeldovich-Raizer, < 1950)

Experimental fact: diffusivity at high temperatures is not constant as in Fourier's law, due to radiation.

$$\frac{d}{dt} \int_{\Omega} c\rho T \, dx = \int_{\partial\Omega} k(T) \nabla T \cdot \mathbf{n} \, dS.$$

Put $k(T) = k_o T^n$, apply Gauss law and you get

$$c\rho \frac{\partial T}{\partial t} = \operatorname{div}(k(T) \nabla T) = c_1 \Delta T^{n+1}.$$

→ When k is not a power we get $T_t = \Delta \Phi(T)$ with $\Phi'(T) = k(T)$.

- Spreading of populations (self-avoiding diffusion) $m \sim 2$.

Applied motivation II

- Plasma radiation $m \geq 4$ (Zeldovich-Raizer, < 1950)

Experimental fact: diffusivity at high temperatures is not constant as in Fourier's law, due to radiation.

$$\frac{d}{dt} \int_{\Omega} c\rho T \, dx = \int_{\partial\Omega} k(T) \nabla T \cdot \mathbf{n} \, dS.$$

Put $k(T) = k_o T^n$, apply Gauss law and you get

$$c\rho \frac{\partial T}{\partial t} = \operatorname{div}(k(T) \nabla T) = c_1 \Delta T^{n+1}.$$

→ When k is not a power we get $T_t = \Delta \Phi(T)$ with $\Phi'(T) = k(T)$.

- Spreading of populations (self-avoiding diffusion) $m \sim 2$.
- Thin films under gravity (no surface tension) $m = 4$.

Applied motivation II

- Plasma radiation $m \geq 4$ (Zeldovich-Raizer, < 1950)

Experimental fact: diffusivity at high temperatures is not constant as in Fourier's law, due to radiation.

$$\frac{d}{dt} \int_{\Omega} c\rho T \, dx = \int_{\partial\Omega} k(T) \nabla T \cdot \mathbf{n} \, dS.$$

Put $k(T) = k_o T^n$, apply Gauss law and you get

$$c\rho \frac{\partial T}{\partial t} = \operatorname{div}(k(T) \nabla T) = c_1 \Delta T^{n+1}.$$

→ When k is not a power we get $T_t = \Delta \Phi(T)$ with $\Phi'(T) = k(T)$.

- Spreading of populations (self-avoiding diffusion) $m \sim 2$.
- Thin films under gravity (no surface tension) $m = 4$.
- Kinetic limits ([Carleman models](#), McKean, PL Lions and Toscani et al.)

Applied motivation II

- Plasma radiation $m \geq 4$ (Zeldovich-Raizer, < 1950)

Experimental fact: diffusivity at high temperatures is not constant as in Fourier's law, due to radiation.

$$\frac{d}{dt} \int_{\Omega} c\rho T \, dx = \int_{\partial\Omega} k(T) \nabla T \cdot \mathbf{n} \, dS.$$

Put $k(T) = k_o T^n$, apply Gauss law and you get

$$c\rho \frac{\partial T}{\partial t} = \operatorname{div}(k(T) \nabla T) = c_1 \Delta T^{n+1}.$$

→ When k is not a power we get $T_t = \Delta \Phi(T)$ with $\Phi'(T) = k(T)$.

- Spreading of populations (self-avoiding diffusion) $m \sim 2$.
- Thin films under gravity (no surface tension) $m = 4$.
- Kinetic limits ([Carleman models](#), McKean, PL Lions and Toscani et al.)
- Many more (boundary layers, geometry).

The basics

- The equation is re-written for $m = 2$ as

$$\frac{1}{2}u_t = u\Delta u + |\nabla u|^2$$

The basics

- The equation is re-written for $m = 2$ as

$$\frac{1}{2}u_t = u\Delta u + |\nabla u|^2$$

- and you can see that for $u \sim 0$ it looks like the eikonal equation

$$u_t = |\nabla u|^2$$

*This is not **parabolic**, but **hyperbolic** (propagation along characteristics).
Mixed type, mixed properties.*

The basics

- The equation is re-written for $m = 2$ as

$$\frac{1}{2}u_t = u\Delta u + |\nabla u|^2$$

- and you can see that for $u \sim 0$ it looks like the eikonal equation

$$u_t = |\nabla u|^2$$

*This is not **parabolic**, but **hyperbolic** (propagation along characteristics).
Mixed type, mixed properties.*

- No big problem when $m > 1$, $m \neq 2$. The pressure transformation gives:

$$v_t = (m - 1)v\Delta v + |\nabla v|^2$$

where $v = cu^{m-1}$ is the pressure; normalization $c = m/(m - 1)$.

This separates $m > 1$ PME - from - $m < 1$ FDE

Planning of the Theory

These are the main topics of mathematical analysis (1958-2006):

- The precise meaning of solution.

Planning of the Theory

These are the main topics of mathematical analysis (1958-2006):

- The precise meaning of solution.
- The nonlinear approach: estimates; functional spaces.

Planning of the Theory

These are the main topics of mathematical analysis (1958-2006):

- The precise meaning of solution.
- The nonlinear approach: estimates; functional spaces.
- Existence, non-existence. Uniqueness, non-uniqueness.

Planning of the Theory

These are the main topics of mathematical analysis (1958-2006):

- The precise meaning of solution.
- The nonlinear approach: estimates; functional spaces.
- Existence, non-existence. Uniqueness, non-uniqueness.
- Regularity of solutions: *is there a limit? C^k for some k ?*

Planning of the Theory

These are the main topics of mathematical analysis (1958-2006):

- The precise meaning of solution.
- The nonlinear approach: estimates; functional spaces.
- Existence, non-existence. Uniqueness, non-uniqueness.
- Regularity of solutions: *is there a limit? C^k for some k ?*
- Regularity and movement of interfaces: *C^k for some k ?*

Planning of the Theory

These are the main topics of mathematical analysis (1958-2006):

- The precise meaning of solution.
- The nonlinear approach: estimates; functional spaces.
- Existence, non-existence. Uniqueness, non-uniqueness.
- Regularity of solutions: *is there a limit? C^k for some k ?*
- Regularity and movement of interfaces: *C^k for some k ?*
- Asymptotic behaviour: *patterns and rates? universal?*

Planning of the Theory

These are the main topics of mathematical analysis (1958-2006):

- The precise meaning of solution.
- The nonlinear approach: estimates; functional spaces.
- Existence, non-existence. Uniqueness, non-uniqueness.
- Regularity of solutions: *is there a limit? C^k for some k ?*
- Regularity and movement of interfaces: *C^k for some k ?*
- Asymptotic behaviour: *patterns and rates? universal?*
- The probabilistic approach. *Nonlinear process. Wasserstein estimates*

Planning of the Theory

These are the main topics of mathematical analysis (1958-2006):

- The precise meaning of solution.
- The nonlinear approach: estimates; functional spaces.
- Existence, non-existence. Uniqueness, non-uniqueness.
- Regularity of solutions: *is there a limit? C^k for some k ?*
- Regularity and movement of interfaces: *C^k for some k ?*
- Asymptotic behaviour: *patterns and rates? universal?*
- The probabilistic approach. *Nonlinear process. Wasserstein estimates*
- Generalization: fast models, inhomogeneous media, anisotropic media, applications to geometry or image processing; other effects.

Planning of the Theory

These are the main topics of mathematical analysis (1958-2006):

- The precise meaning of solution.
- The nonlinear approach: estimates; functional spaces.
- Existence, non-existence. Uniqueness, non-uniqueness.
- Regularity of solutions: *is there a limit? C^k for some k ?*
- Regularity and movement of interfaces: *C^k for some k ?*
- Asymptotic behaviour: *patterns and rates? universal?*
- The probabilistic approach. *Nonlinear process. Wasserstein estimates*
- Generalization: fast models, inhomogeneous media, anisotropic media, applications to geometry or image processing; other effects.

Barenblatt profiles (ZKB)

- These profiles are the alternative to the Gaussian profiles.

Barenblatt profiles (ZKB)

- These profiles are the alternative to the Gaussian profiles.
- They are source solutions. *Source* means that $u(x, t) \rightarrow M \delta(x)$ as $t \rightarrow 0$.

Barenblatt profiles (ZKB)

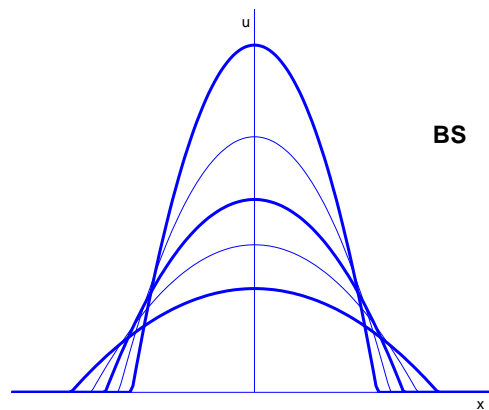
- These profiles are the alternative to the Gaussian profiles.
- They are source solutions. *Source* means that $u(x, t) \rightarrow M \delta(x)$ as $t \rightarrow 0$.
- Explicit formulas (1950): $\left(\alpha = \frac{n}{2+n(m-1)}, \beta = \frac{1}{2+n(m-1)} < 1/2\right)$

$$\mathbf{B}(x, t; M) = t^{-\alpha} \mathbf{F}(x/t^\beta), \quad \mathbf{F}(\xi) = (C - k\xi^2)_+^{1/(m-1)}$$

Barenblatt profiles (ZKB)

- These profiles are the alternative to the Gaussian profiles.
- They are source solutions. *Source* means that $u(x, t) \rightarrow M \delta(x)$ as $t \rightarrow 0$.
- Explicit formulas (1950): $\left(\alpha = \frac{n}{2+n(m-1)}, \beta = \frac{1}{2+n(m-1)} < 1/2\right)$

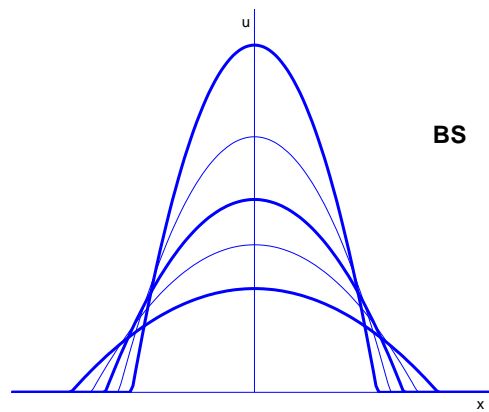
$$\mathbf{B}(x, t; M) = t^{-\alpha} \mathbf{F}(x/t^\beta), \quad \mathbf{F}(\xi) = (C - k\xi^2)_+^{1/(m-1)}$$



Barenblatt profiles (ZKB)

- These profiles are the alternative to the Gaussian profiles.
- They are source solutions. *Source* means that $u(x, t) \rightarrow M \delta(x)$ as $t \rightarrow 0$.
- Explicit formulas (1950): $\left(\alpha = \frac{n}{2+n(m-1)}, \beta = \frac{1}{2+n(m-1)} < 1/2 \right)$

$$\mathbf{B}(x, t; M) = t^{-\alpha} \mathbf{F}(x/t^\beta), \quad \mathbf{F}(\xi) = (C - k\xi^2)_+^{1/(m-1)}$$



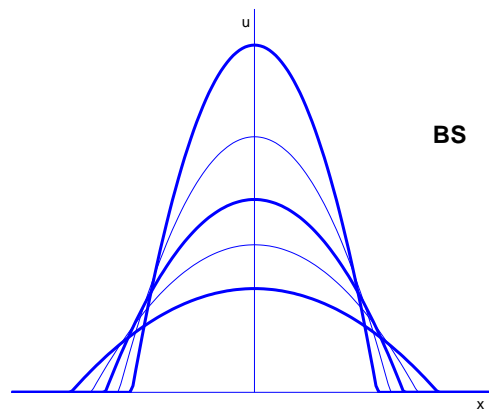
Height $u = Ct^{-\alpha}$ Free boundary at distance $|x| = ct^\beta$

Scaling law; anomalous diffusion versus Brownian motion

Barenblatt profiles (ZKB)

- These profiles are the alternative to the Gaussian profiles.
- They are source solutions. *Source* means that $u(x, t) \rightarrow M \delta(x)$ as $t \rightarrow 0$.
- Explicit formulas (1950): $\left(\alpha = \frac{n}{2+n(m-1)}, \beta = \frac{1}{2+n(m-1)} < 1/2 \right)$

$$\mathbf{B}(x, t; M) = t^{-\alpha} \mathbf{F}(x/t^\beta), \quad \mathbf{F}(\xi) = (C - k\xi^2)_+^{1/(m-1)}$$



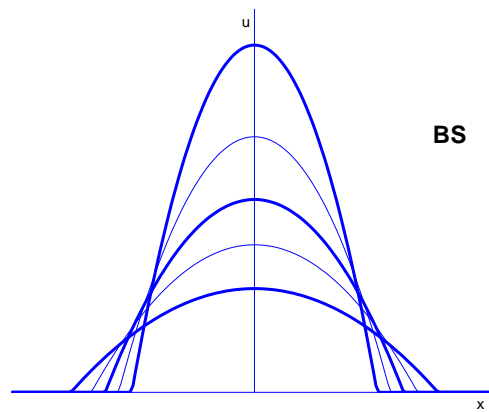
Height $u = Ct^{-\alpha}$ Free boundary at distance $|x| = ct^\beta$

Scaling law; anomalous diffusion versus Brownian motion

Barenblatt profiles (ZKB)

- These profiles are the alternative to the Gaussian profiles.
- They are source solutions. *Source* means that $u(x, t) \rightarrow M \delta(x)$ as $t \rightarrow 0$.
- Explicit formulas (1950): $\left(\alpha = \frac{n}{2+n(m-1)}, \beta = \frac{1}{2+n(m-1)} < 1/2 \right)$

$$\mathbf{B}(x, t; M) = t^{-\alpha} \mathbf{F}(x/t^\beta), \quad \mathbf{F}(\xi) = (C - k\xi^2)_+^{1/(m-1)}$$



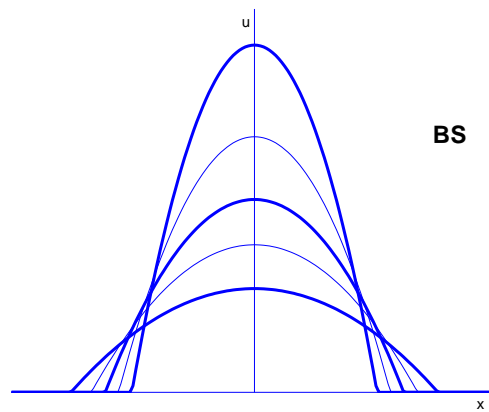
Height $u = Ct^{-\alpha}$ Free boundary at distance $|x| = ct^\beta$

Scaling law; anomalous diffusion versus Brownian motion

Barenblatt profiles (ZKB)

- These profiles are the alternative to the Gaussian profiles.
- They are source solutions. *Source* means that $u(x, t) \rightarrow M \delta(x)$ as $t \rightarrow 0$.
- Explicit formulas (1950): $\left(\alpha = \frac{n}{2+n(m-1)}, \beta = \frac{1}{2+n(m-1)} < 1/2 \right)$

$$\mathbf{B}(x, t; M) = t^{-\alpha} \mathbf{F}(x/t^\beta), \quad \mathbf{F}(\xi) = (C - k\xi^2)_+^{1/(m-1)}$$



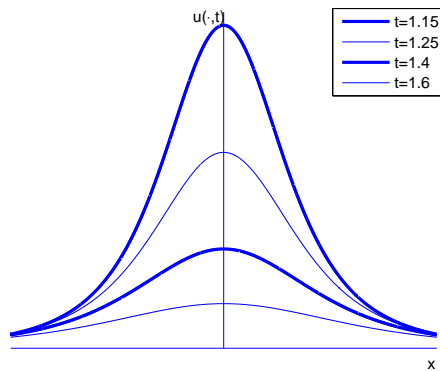
Height $u = Ct^{-\alpha}$ Free boundary at distance $|x| = ct^\beta$

Scaling law; anomalous diffusion versus Brownian motion

FDE profiles

- We again have explicit formulas for $1 > m > (n - 2)/n$:

$$\mathbf{B}(x, t; M) = t^{-\alpha} \mathbf{F}(x/t^\beta), \quad \mathbf{F}(\xi) = \frac{1}{(C + k\xi^2)^{1/(1-m)}}$$



$$\alpha = \frac{n}{2-n(1-m)}$$

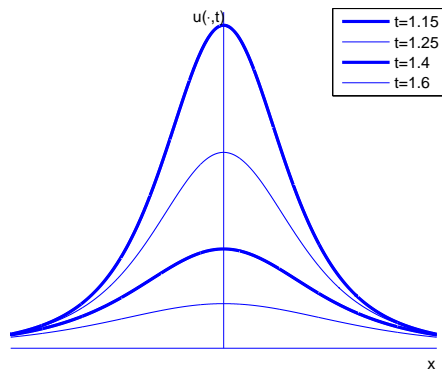
$$\beta = \frac{1}{2-n(1-m)} > 1/2$$

Solutions for $m > 1$ with **fat tails** (polynomial decay; anomalous distributions)

FDE profiles

- We again have explicit formulas for $1 > m > (n - 2)/n$:

$$\mathbf{B}(x, t; M) = t^{-\alpha} \mathbf{F}(x/t^\beta), \quad \mathbf{F}(\xi) = \frac{1}{(C + k\xi^2)^{1/(1-m)}}$$



$$\alpha = \frac{n}{2-n(1-m)}$$

$$\beta = \frac{1}{2-n(1-m)} > 1/2$$

Solutions for $m > 1$ with **fat tails** (polynomial decay; anomalous distributions)

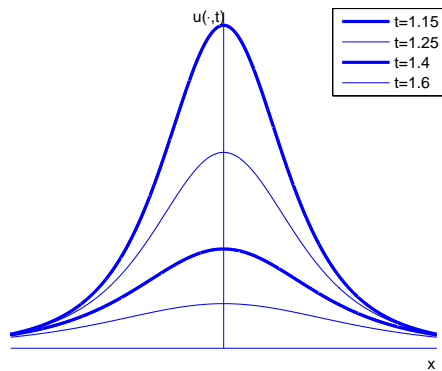
- **Big problem:** What happens for $m < (n - 2)/n$? Most active branch of PME/FDE. New asymptotics, extinction, new functional properties, new geometry and physics.

Many authors: [J. King, geometers](#), ... → my book “Smoothing”.

FDE profiles

- We again have explicit formulas for $1 > m > (n - 2)/n$:

$$\mathbf{B}(x, t; M) = t^{-\alpha} \mathbf{F}(x/t^\beta), \quad \mathbf{F}(\xi) = \frac{1}{(C + k\xi^2)^{1/(1-m)}}$$



$$\alpha = \frac{n}{2-n(1-m)}$$

$$\beta = \frac{1}{2-n(1-m)} > 1/2$$

Solutions for $m > 1$ with **fat tails** (polynomial decay; anomalous distributions)

- **Big problem:** What happens for $m < (n - 2)/n$? Most active branch of PME/FDE. New asymptotics, extinction, new functional properties, new geometry and physics.

Many authors: [J. King, geometers](#), ... → my book “Smoothing”.

Concept of solution

There are many concepts of generalized solution of the PME:

- **Classical solution:** only in nondegenerate situations, $u > 0$.

Concept of solution

There are many concepts of generalized solution of the PME:

- **Classical solution:** only in nondegenerate situations, $u > 0$.
- **Limit solution:** physical, but depends on the approximation (?).

Concept of solution

There are many concepts of generalized solution of the PME:

- **Classical solution:** only in nondegenerate situations, $u > 0$.
- **Limit solution:** physical, but depends on the approximation (?).
- **Weak solution** Test against smooth functions and eliminate derivatives on the unknown function; it is the mainstream; (Oleinik, 1958)

$$\int \int (u \eta_t - \nabla u^m \cdot \nabla \eta) dx dt + \int u_0(x) \eta(x, 0) dx = 0.$$

Very weak

$$\int \int (u \eta_t + u^m \Delta \eta) dx dt + \int u_0(x) \eta(x, 0) dx = 0.$$

More on concepts of solution

Solutions are not always weak:

- **Strong solution.** More regular than weak but not classical: weak derivatives are L^p functions. *Big benefit: usual calculus is possible.*

More on concepts of solution

Solutions are not always weak:

- **Strong solution.** More regular than weak but not classical: weak derivatives are L^p functions. *Big benefit: usual calculus is possible.*
- **Semigroup solution / mild solution.** The typical product of functional discretization schemes: $u = \{u_n\}_n$, $u_n = u(\cdot, t_n)$,

$$u_t = \Delta\Phi(u), \quad \frac{u_n - u_{n-1}}{h} - \Delta\Phi(u_n) = 0$$

More on concepts of solution

Solutions are not always weak:

- **Strong solution.** More regular than weak but not classical: weak derivatives are L^p functions. *Big benefit: usual calculus is possible.*
- **Semigroup solution / mild solution.** The typical product of functional discretization schemes: $u = \{u_n\}_n$, $u_n = u(\cdot, t_n)$,

$$u_t = \Delta\Phi(u), \quad \frac{u_n - u_{n-1}}{h} - \Delta\Phi(u_n) = 0$$

Now put $f := u_{n-1}$, $u := u_n$, and $v = \Phi(u)$, $u = \beta(v)$:

$$-h\Delta\Phi(u) + u = f, \quad \boxed{-h\Delta v + \beta(v) = f.}$$

"Nonlinear elliptic equations"; Crandall-Liggett
Theorems Ambrosio, Savarè, Nochetto

More on concepts of solution

Solutions are not always weak:

- **Strong solution.** More regular than weak but not classical: weak derivatives are L^p functions. *Big benefit: usual calculus is possible.*
- **Semigroup solution / mild solution.** The typical product of functional discretization schemes: $u = \{u_n\}_n$, $u_n = u(\cdot, t_n)$,

$$u_t = \Delta\Phi(u), \quad \frac{u_n - u_{n-1}}{h} - \Delta\Phi(u_n) = 0$$

Now put $f := u_{n-1}$, $u := u_n$, and $v = \Phi(u)$, $u = \beta(v)$:

$$-h\Delta\Phi(u) + u = f, \quad \boxed{-h\Delta v + \beta(v) = f.}$$

"Nonlinear elliptic equations"; Crandall-Liggett
Theorems Ambrosio, Savarè, Nochetto

More on concepts of solution II

Solutions of more complicated equations need new concepts:

- **Viscosity solution** Two ideas: (1) add artificial viscosity and pass to the limit; (2) viscosity concept of Crandall-Evans-Lions (1984); adapted to PME by Caffarelli-Vazquez (1999).

More on concepts of solution II

Solutions of more complicated equations need new concepts:

- **Viscosity solution** Two ideas: (1) add artificial viscosity and pass to the limit; (2) viscosity concept of Crandall-Evans-Lions (1984); adapted to PME by Caffarelli-Vazquez (1999).
- **Entropy solution** (Kruzhkov, 1968). Invented for conservation laws; it identifies unique physical solution from **spurious** weak solutions. It is useful for general models degenerate diffusion-convection models;

More on concepts of solution II

Solutions of more complicated equations need new concepts:

- **Viscosity solution** Two ideas: (1) add artificial viscosity and pass to the limit; (2) viscosity concept of Crandall-Evans-Lions (1984); adapted to PME by Caffarelli-Vazquez (1999).
- **Entropy solution** (Kruzhkov, 1968). Invented for conservation laws; it identifies unique physical solution from **spurious** weak solutions. It is useful for general models degenerate diffusion-convection models;
- **Renormalized solution** (Di Perna - Lions).

More on concepts of solution II

Solutions of more complicated equations need new concepts:

- **Viscosity solution** Two ideas: (1) add artificial viscosity and pass to the limit; (2) viscosity concept of Crandall-Evans-Lions (1984); adapted to PME by Caffarelli-Vazquez (1999).
- **Entropy solution** (Kruzhkov, 1968). Invented for conservation laws; it identifies unique physical solution from **spurious** weak solutions. It is useful for general models degenerate diffusion-convection models;
- **Renormalized solution** (Di Perna - Lions).
- **BV solution** (Volpert-Hudjaev).

More on concepts of solution II

Solutions of more complicated equations need new concepts:

- **Viscosity solution** Two ideas: (1) add artificial viscosity and pass to the limit; (2) viscosity concept of Crandall-Evans-Lions (1984); adapted to PME by Caffarelli-Vazquez (1999).
- **Entropy solution** (Kruzhkov, 1968). Invented for conservation laws; it identifies unique physical solution from **spurious** weak solutions. It is useful for general models degenerate diffusion-convection models;
- **Renormalized solution** (Di Perna - Lions).
- **BV solution** (Volpert-Hudjaev).
- **Kinetic solutions** (Perthame,...).

The main estimates

- Boundedness estimates: for every $p \geq 1$

$$I_p(t) = \int_{\mathbf{R}^n} u^p(x, t) dx \leq I_p(0)$$

and goes down with time

The main estimates

- Boundedness estimates: for every $p \geq 1$

$$I_p(t) = \int_{\mathbf{R}^n} u^p(x, t) dx \leq I_p(0)$$

and goes down with time

- Derivative estimates for compactness: The basic L^2 space estimate

$$\frac{1}{m+1} \iint_{Q_T} |\nabla u^m|^2 dx dt + \int_{\Omega} |u(x, t)|^{m+1} dx = \int_{\Omega} |u_0|^{m+1} dx$$

Idea: multiplier is u^m

The main estimates

- Boundedness estimates: for every $p \geq 1$

$$I_p(t) = \int_{\mathbf{R}^n} u^p(x, t) dx \leq I_p(0)$$

and goes down with time

- Derivative estimates for compactness: The basic L^2 space estimate

$$\frac{1}{m+1} \iint_{Q_T} |\nabla u^m|^2 dx dt + \int_{\Omega} |u(x, t)|^{m+1} dx = \int_{\Omega} |u_0|^{m+1} dx$$

Idea: multiplier is u^m

- The time derivative estimate.

$$c \iint_{Q_T} |(u_t^{(m+1)/2})|^2 dx dt + \int_{\Omega} |\nabla u(x, t)^m|^2 dx = \int_{\Omega} |\nabla u_0(x)^m|^2 dx$$

Idea: multiplier is $(u^m)_t$

The main estimates

- Boundedness estimates: for every $p \geq 1$

$$I_p(t) = \int_{\mathbf{R}^n} u^p(x, t) dx \leq I_p(0)$$

and goes down with time

- Derivative estimates for compactness: The basic L^2 space estimate

$$\frac{1}{m+1} \iint_{Q_T} |\nabla u^m|^2 dx dt + \int_{\Omega} |u(x, t)|^{m+1} dx = \int_{\Omega} |u_0|^{m+1} dx$$

Idea: multiplier is u^m

- The time derivative estimate.

$$c \iint_{Q_T} |(u_t^{(m+1)/2})|^2 dx dt + \int_{\Omega} |\nabla u(x, t)^m|^2 dx = \int_{\Omega} |\nabla u_0(x)^m|^2 dx$$

Idea: multiplier is $(u^m)_t$

The main estimates

- Boundedness estimates: for every $p \geq 1$

$$I_p(t) = \int_{\mathbf{R}^n} u^p(x, t) dx \leq I_p(0)$$

and goes down with time

- Derivative estimates for compactness: The basic L^2 space estimate

$$\frac{1}{m+1} \iint_{Q_T} |\nabla u^m|^2 dx dt + \int_{\Omega} |u(x, t)|^{m+1} dx = \int_{\Omega} |u_0|^{m+1} dx$$

Idea: multiplier is u^m

- The time derivative estimate.

$$c \iint_{Q_T} |(u_t^{(m+1)/2})|^2 dx dt + \int_{\Omega} |\nabla u(x, t)^m|^2 dx = \int_{\Omega} |\nabla u_0(x)^m|^2 dx$$

Idea: multiplier is $(u^m)_t$

The L^1 estimate. Contraction. Existence

- Problem: They are not *stability estimates* for differences.

The L^1 estimate. Contraction. Existence

- Problem: They are not **stability estimates** for differences.
- The main stability estimate (**L^1 contraction**):

$$\frac{d}{dt} \int_{\Omega} |u_1(x, t) - u_2(x, t)| dx \leq 0$$

The L^1 estimate. Contraction. Existence

- Problem: They are not **stability estimates** for differences.
- The main stability estimate (**L^1 contraction**):

$$\frac{d}{dt} \int_{\Omega} |u_1(x, t) - u_2(x, t)| dx \leq 0$$

- **Proof.** Multiply the difference of the equations for u_1 and u_2 by $\zeta = h_{\epsilon}(w)$, where h_{ϵ} is a smooth version of Heaviside's step function, and $w = u_1^m - u_2^m$, $u = u_1 - u_2$. Then,

$$\int u_t h(w) dx = \int \Delta w h(w) dx = - \int h'(w) |\nabla w|^2 dx \leq 0.$$

Now let $h_{\epsilon} \rightarrow h = \text{sign}^+$. Observe that $\text{sign}(u_1 - u_2) = \text{sign}(u_1^m - u_2^m)$. Then

$$\frac{d}{dt} \int (u_1 - u_2)_+ dx = \int u_t h(u) dx \leq 0$$

The L^1 estimate. Contraction. Existence

- Problem: They are not **stability estimates** for differences.
- The main stability estimate (**L^1 contraction**):

$$\frac{d}{dt} \int_{\Omega} |u_1(x, t) - u_2(x, t)| dx \leq 0$$

- **Proof.** Multiply the difference of the equations for u_1 and u_2 by $\zeta = h_{\epsilon}(w)$, where h_{ϵ} is a smooth version of Heaviside's step function, and $w = u_1^m - u_2^m$, $u = u_1 - u_2$. Then,

$$\int u_t h(w) dx = \int \Delta w h(w) dx = - \int h'(w) |\nabla w|^2 dx \leq 0.$$

Now let $h_{\epsilon} \rightarrow h = \text{sign}^+$. Observe that $\text{sign}(u_1 - u_2) = \text{sign}(u_1^m - u_2^m)$. Then

$$\frac{d}{dt} \int (u_1 - u_2)_+ dx = \int u_t h(u) dx \leq 0$$

- Contraction is also true in H^{-1} and in the Wasserstein W_2 space

The standard solutions

Let $\Omega = \mathbb{R}^n$ or bounded set with zero Dirichlet boundary data, $n \geq 1$, $0 < T \leq \infty$. Let us consider the PME with $m > 1$.

- For every $u_0 \in L^1(\Omega)$, $u_0 \geq 0$, there exists a weak solution such that $u, u^m \in L^2_{x,t}$ and $\nabla u^m \in L^2_{x,t}$.

The standard solutions

Let $\Omega = \mathbb{R}^n$ or bounded set with zero Dirichlet boundary data, $n \geq 1$, $0 < T \leq \infty$. Let us consider the PME with $m > 1$.

- For every $u_0 \in L^1(\Omega)$, $u_0 \geq 0$, there exists a weak solution such that $u, u^m \in L^2_{x,t}$ and $\nabla u^m \in L^2_{x,t}$.
- The weak solution is a strong solution in the following sense:
 - (i) $u^m \in L^2(\tau, \infty : H^1_0(\Omega))$ for every $\tau > 0$;
 - (ii) u_t and $\Delta u^m \in L^1_{loc}(0, \infty : L^1(\Omega))$ and $u_t = \Delta u^m$ a.e. in Q ;
 - (iii) $u \in C([0, T) : L^1(\Omega))$ and $u(0) = u_0$.

The standard solutions

Let $\Omega = \mathbf{R}^n$ or bounded set with zero Dirichlet boundary data, $n \geq 1$, $0 < T \leq \infty$. Let us consider the PME with $m > 1$.

- For every $u_0 \in L^1(\Omega)$, $u_0 \geq 0$, there exists a weak solution such that $u, u^m \in L^2_{x,t}$ and $\nabla u^m \in L^2_{x,t}$.
- The weak solution is a strong solution in the following sense:
 - (i) $u^m \in L^2(\tau, \infty : H^1_0(\Omega))$ for every $\tau > 0$;
 - (ii) u_t and $\Delta u^m \in L^1_{loc}(0, \infty : L^1(\Omega))$ and $u_t = \Delta u^m$ a.e. in Q ;
 - (iii) $u \in C([0, T) : L^1(\Omega))$ and $u(0) = u_0$.
- We also have bounded solutions that decay in time

$$0 \leq u(x, t) \leq C \|u_0\|_1^{2\beta} t^{-\alpha}$$

ultra-contractivity generalized to nonlinear cases

The standard solutions

Let $\Omega = \mathbf{R}^n$ or bounded set with zero Dirichlet boundary data, $n \geq 1$, $0 < T \leq \infty$. Let us consider the PME with $m > 1$.

- For every $u_0 \in L^1(\Omega)$, $u_0 \geq 0$, there exists a weak solution such that $u, u^m \in L^2_{x,t}$ and $\nabla u^m \in L^2_{x,t}$.
- The weak solution is a strong solution in the following sense:
 - (i) $u^m \in L^2(\tau, \infty : H^1_0(\Omega))$ for every $\tau > 0$;
 - (ii) u_t and $\Delta u^m \in L^1_{loc}(0, \infty : L^1(\Omega))$ and $u_t = \Delta u^m$ a.e. in Q ;
 - (iii) $u \in C([0, T) : L^1(\Omega))$ and $u(0) = u_0$.
- We also have bounded solutions that decay in time

$$0 \leq u(x, t) \leq C \|u_0\|_1^{2\beta} t^{-\alpha}$$

ultra-contractivity generalized to nonlinear cases

Regularity results

- The universal estimate holds (Aronson-Bénilan, 79):

$$\Delta v \geq -C/t.$$

$v \sim u^{m-1}$ is the pressure.

Regularity results

- The universal estimate holds (Aronson-Bénilan, 79):

$$\Delta v \geq -C/t.$$

$v \sim u^{m-1}$ is the pressure.

- (Caffarelli-Friedman, 1982) C^α regularity: there is an $\alpha \in (0, 1)$ such that a bounded solution defined in a cube is C^α continuous.

Regularity results

- The universal estimate holds (Aronson-Bénilan, 79):

$$\Delta v \geq -C/t.$$

$v \sim u^{m-1}$ is the pressure.

- (Caffarelli-Friedman, 1982) C^α regularity: there is an $\alpha \in (0, 1)$ such that a bounded solution defined in a cube is C^α continuous.
- If there is an interface Γ , it is also C^α continuous in space time.

Regularity results

- The universal estimate holds (Aronson-Bénilan, 79):

$$\Delta v \geq -C/t.$$

$v \sim u^{m-1}$ is the pressure.

- (Caffarelli-Friedman, 1982) C^α regularity: there is an $\alpha \in (0, 1)$ such that a bounded solution defined in a cube is C^α continuous.
- If there is an interface Γ , it is also C^α continuous in space time.
- How far can you go? Free boundaries are stationary (metastable) if initial profile is quadratic near $\partial\Omega$: $u_0(x) = O(d^2)$. This is called **waiting time**. Characterized by V. in 1983. *Visually interesting in thin films spreading on a table*. Existence of corner points possible when metastable, \rightarrow no C^1 Aronson-Caffarelli-V. Regularity stops here in $n = 1$

Regularity results

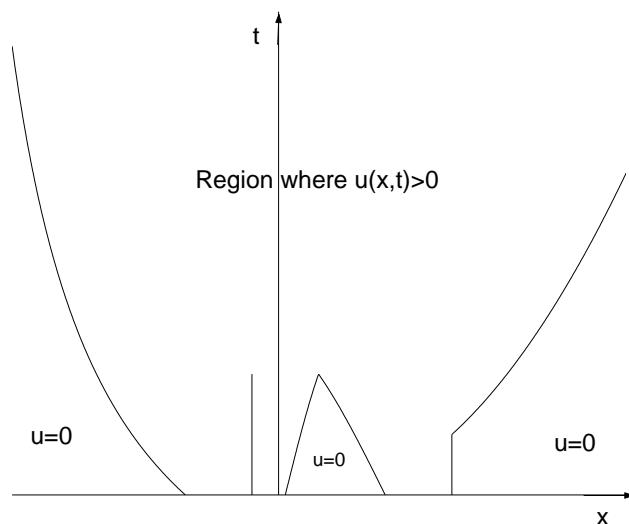
- The universal estimate holds (Aronson-Bénilan, 79):

$$\Delta v \geq -C/t.$$

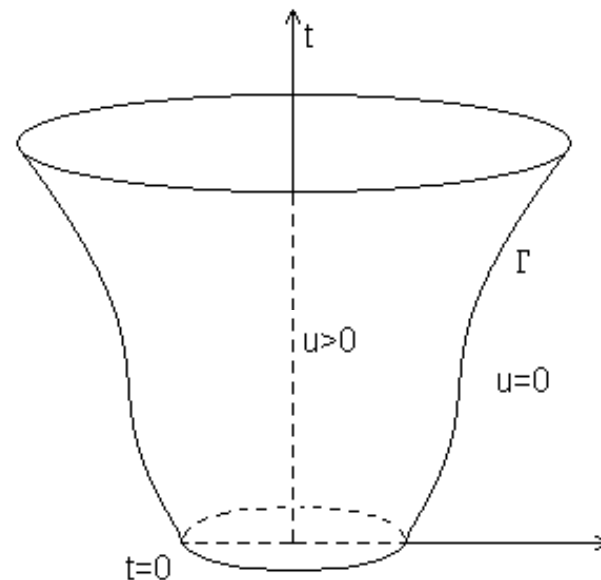
$v \sim u^{m-1}$ is the pressure.

- (Caffarelli-Friedman, 1982) C^α regularity: there is an $\alpha \in (0, 1)$ such that a bounded solution defined in a cube is C^α continuous.
- If there is an interface Γ , it is also C^α continuous in space time.
- How far can you go? Free boundaries are stationary (metastable) if initial profile is quadratic near $\partial\Omega$: $u_0(x) = O(d^2)$. This is called **waiting time**. Characterized by V. in 1983. *Visually interesting in thin films spreading on a table*. Existence of corner points possible when metastable, \rightarrow no C^1 Aronson-Caffarelli-V. Regularity stops here in $n = 1$

Free Boundaries in several dimensions



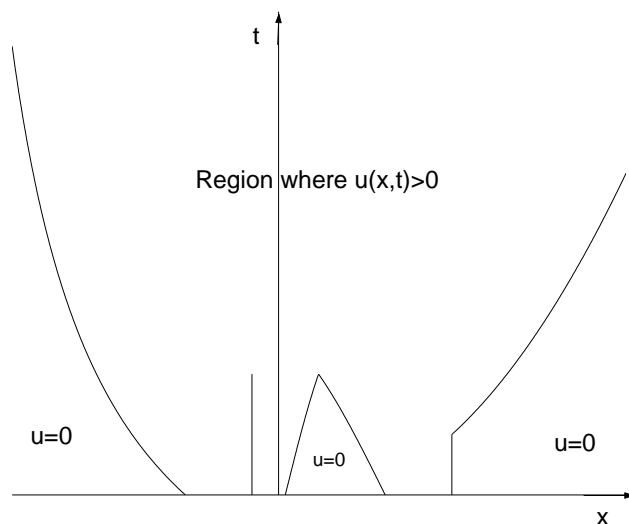
A complex free boundary in 1-D



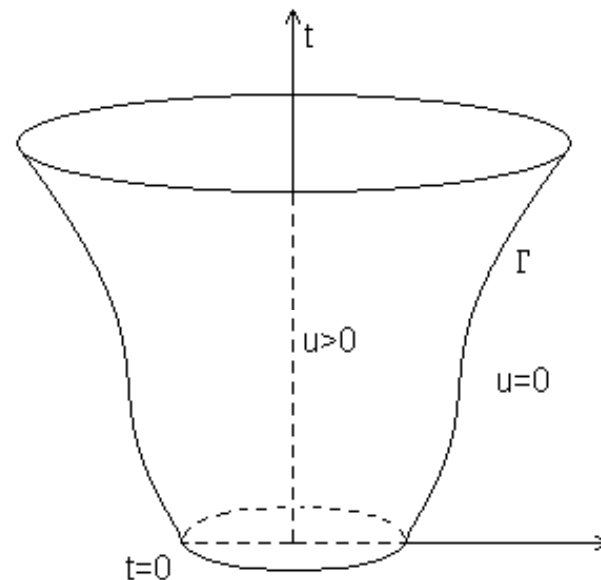
A regular free boundary in n-D

- (Caffarelli-Vazquez-Wolanski, 1987) If u_0 has compact support, then after some time T the interface and the solutions are $C^{1,\alpha}$.

Free Boundaries in several dimensions



A complex free boundary in 1-D



A regular free boundary in n-D

- (Caffarelli-Vazquez-Wolanski, 1987) If u_0 has compact support, then after some time T the interface and the solutions are $C^{1,\alpha}$.
- (Koch, thesis, 1997) If u_0 is transversal then FB is C^∞ after T . Pressure is “laterally” C^∞ . *it is a broken profile always when it moves.*

Free Boundaries II. Holes

- A free boundary with a hole in 2D, 3D is the way of showing that focusing accelerates the viscous fluid so that the speed becomes infinite. This is **blow-up** for $v \sim \nabla u^{m-1}$.
The setup is a viscous fluid on a table occupying an annulus of radii r_1 and r_2 . As time passes $r_2(t)$ grows and $r_1(t)$ goes to the origin. As $t \rightarrow T$, the time the hole disappears, the speed $r_1'(t) \rightarrow -\infty$.

Free Boundaries II. Holes

- A free boundary with a hole in 2D, 3D is the way of showing that focusing accelerates the viscous fluid so that the speed becomes infinite. This is **blow-up** for $v \sim \nabla u^{m-1}$.

The setup is a viscous fluid on a table occupying an annulus of radii r_1 and r_2 . As time passes $r_2(t)$ grows and $r_1(t)$ goes to the origin. As $t \rightarrow T$, the time the hole disappears, the speed $r_1'(t) \rightarrow -\infty$.

- There is a **semi-explicit solution** displaying that behaviour

$$u(x, t) = (T - t)^\alpha F(x(T - t)^{-\beta}).$$

The interface is then $r_1(t) = a(T - t)^\beta$. It is proved that $\beta < 1$. Aronson and Graveleau, 1993. Later Angenent, Aronson, ..., Vazquez,

III. Asymptotics

Asymptotic behaviour

Nonlinear Central Limit Theorem

• Choice of domain: \mathbb{R}^n . Choice of data: $u_0(x) \in L^1(\mathbb{R}^n)$. We can write

$$u_t = \Delta(|u|^{m-1}u) + f$$

Let us put $f \in L^1_{x,t}$. Let $M = \int u_0(x) dx + \iint f dxdt$.

Asymptotic behaviour

Nonlinear Central Limit Theorem

- Choice of domain: \mathbb{R}^n . Choice of data: $u_0(x) \in L^1(\mathbb{R}^n)$. We can write

$$u_t = \Delta(|u|^{m-1}u) + f$$

Let us put $f \in L^1_{x,t}$. Let $M = \int u_0(x) dx + \iint f dx dt$.

- Asymptotic Theorem** [Kamin and Friedman, 1980; V. 2001] *Let $B(x, t; M)$ be the Barenblatt with the asymptotic mass M ; u converges to B after renormalization*

$$t^\alpha |u(x, t) - B(x, t)| \rightarrow 0$$

For every $p \geq 1$ we have

$$\|u(t) - B(t)\|_p = o(t^{-\alpha/p'}), \quad p' = p/(p-1).$$

Note: α and $\beta = \alpha/n = 1/(2 + n(m-1))$ are the zooming exponents as in $B(x, t)$.

Asymptotic behaviour

Nonlinear Central Limit Theorem

- Choice of domain: \mathbb{R}^n . Choice of data: $u_0(x) \in L^1(\mathbb{R}^n)$. We can write

$$u_t = \Delta(|u|^{m-1}u) + f$$

Let us put $f \in L^1_{x,t}$. Let $M = \int u_0(x) dx + \iint f dx dt$.

- Asymptotic Theorem** [Kamin and Friedman, 1980; V. 2001] *Let $B(x, t; M)$ be the Barenblatt with the asymptotic mass M ; u converges to B after renormalization*

$$t^\alpha |u(x, t) - B(x, t)| \rightarrow 0$$

For every $p \geq 1$ we have

$$\|u(t) - B(t)\|_p = o(t^{-\alpha/p'}), \quad p' = p/(p-1).$$

Note: α and $\beta = \alpha/n = 1/(2 + n(m-1))$ are the zooming exponents as in $B(x, t)$.

- Starting result by FK takes $u_0 \geq 0$, compact support and $f = 0$

Asymptotic behaviour. Picture

+ The rate cannot be improved without more information on u_0

+ m also less than 1 but supercritical (\rightarrow with even better convergence called **relative error convergence**)

$m < (n - 2)/n$ has big surprises;

$m = 0 \rightarrow u_t = \Delta \log u \rightarrow$ Ricci flow with strange properties;

Proof works for p -Laplacian flow

Asymptotic behaviour. II

- **The rates.** Carrillo-Toscani 2000. Using entropy functional with entropy dissipation control you can prove decay rates when $\int u_0(x)|x|^2 dx < \infty$ (finite variance):

$$\|u(t) - B(t)\|_1 = O(t^{-\delta}),$$

We would like to have $\delta = 1$. This problem is still open for $m > 2$. New results by JA Carrillo, McCann, Del Pino, Dolbeault, Vazquez et al. include $m < 1$.

Asymptotic behaviour. II

- **The rates.** Carrillo-Toscani 2000. Using entropy functional with entropy dissipation control you can prove decay rates when $\int u_0(x)|x|^2 dx < \infty$ (finite variance):

$$\|u(t) - B(t)\|_1 = O(t^{-\delta}),$$

We would like to have $\delta = 1$. This problem is still open for $m > 2$. New results by JA Carrillo, McCann, Del Pino, Dolbeault, Vazquez et al. include $m < 1$.

- **Eventual geometry, concavity and convexity** Result by Lee and Vazquez (2003): Here we assume compact support. There exists a time after which the **pressure is concave, the domain convex, the level sets convex** and

$$t \|(D^2 v(\cdot, t) - k\mathbf{I})\|_\infty \rightarrow 0$$

uniformly in the support. The solution has only one maximum. Inner Convergence in C^∞ .

Asymptotic behaviour. II

- **The rates.** Carrillo-Toscani 2000. Using entropy functional with entropy dissipation control you can prove decay rates when $\int u_0(x)|x|^2 dx < \infty$ (finite variance):

$$\|u(t) - B(t)\|_1 = O(t^{-\delta}),$$

We would like to have $\delta = 1$. This problem is still open for $m > 2$. New results by JA Carrillo, McCann, Del Pino, Dolbeault, Vazquez et al. include $m < 1$.

- **Eventual geometry, concavity and convexity** Result by Lee and Vazquez (2003): Here we assume compact support. There exists a time after which the **pressure is concave, the domain convex, the level sets convex** and

$$t \|(D^2 v(\cdot, t) - k\mathbf{I})\|_\infty \rightarrow 0$$

uniformly in the support. The solution has only one maximum. Inner Convergence in C^∞ .

Asymptotic behaviour. II

- **The rates.** Carrillo-Toscani 2000. Using entropy functional with entropy dissipation control you can prove decay rates when $\int u_0(x)|x|^2 dx < \infty$ (finite variance):

$$\|u(t) - B(t)\|_1 = O(t^{-\delta}),$$

We would like to have $\delta = 1$. This problem is still open for $m > 2$. New results by JA Carrillo, McCann, Del Pino, Dolbeault, Vazquez et al. include $m < 1$.

- **Eventual geometry, concavity and convexity** Result by Lee and Vazquez (2003): Here we assume compact support. There exists a time after which the **pressure is concave, the domain convex, the level sets convex** and

$$t \|(D^2 v(\cdot, t) - k\mathbf{I})\|_\infty \rightarrow 0$$

uniformly in the support. The solution has only one maximum. Inner Convergence in C^∞ .

Calculations of the entropy rates

- We rescale the function as $u(x, t) = r(t)^n \rho(y r(t), s)$ where $r(t)$ is the Barenblatt radius at $t + 1$, and “new time” is $s = \log(1 + t)$. Equation becomes

$$\rho_s = \operatorname{div} \left(\rho (\nabla \rho^{m-1} + \frac{c}{2} \nabla y^2) \right).$$

Calculations of the entropy rates

- We rescale the function as $u(x, t) = r(t)^n \rho(y r(t), s)$ where $r(t)$ is the Barenblatt radius at $t + 1$, and “new time” is $s = \log(1 + t)$. Equation becomes

$$\rho_s = \operatorname{div} \left(\rho (\nabla \rho^{m-1} + \frac{c}{2} \nabla y^2) \right).$$

- Then define the entropy

$$E(u)(t) = \int \left(\frac{1}{m} \rho^m + \frac{c}{2} \rho y^2 \right) dy$$

The minimum of entropy is identified as the Barenblatt profile.

Calculations of the entropy rates

- We rescale the function as $u(x, t) = r(t)^n \rho(y r(t), s)$ where $r(t)$ is the Barenblatt radius at $t + 1$, and “new time” is $s = \log(1 + t)$. Equation becomes

$$\rho_s = \operatorname{div} \left(\rho (\nabla \rho^{m-1} + \frac{c}{2} \nabla y^2) \right).$$

- Then define the entropy

$$E(u)(t) = \int \left(\frac{1}{m} \rho^m + \frac{c}{2} \rho y^2 \right) dy$$

The minimum of entropy is identified as the Barenblatt profile.

- Calculate

$$\frac{dE}{ds} = - \int \rho |\nabla \rho^{m-1} + c y|^2 dy = -D$$

Moreover,

$$\frac{dD}{ds} = -R, \quad R \sim \lambda D.$$

*We conclude exponential decay of D and E in **new time** s , which is potential in **real time** t .*

Calculations of the entropy rates

- We rescale the function as $u(x, t) = r(t)^n \rho(y r(t), s)$ where $r(t)$ is the Barenblatt radius at $t + 1$, and “new time” is $s = \log(1 + t)$. Equation becomes

$$\rho_s = \operatorname{div} \left(\rho (\nabla \rho^{m-1} + \frac{c}{2} \nabla y^2) \right).$$

- Then define the entropy

$$E(u)(t) = \int \left(\frac{1}{m} \rho^m + \frac{c}{2} \rho y^2 \right) dy$$

The minimum of entropy is identified as the Barenblatt profile.

- Calculate

$$\frac{dE}{ds} = - \int \rho |\nabla \rho^{m-1} + cy|^2 dy = -D$$

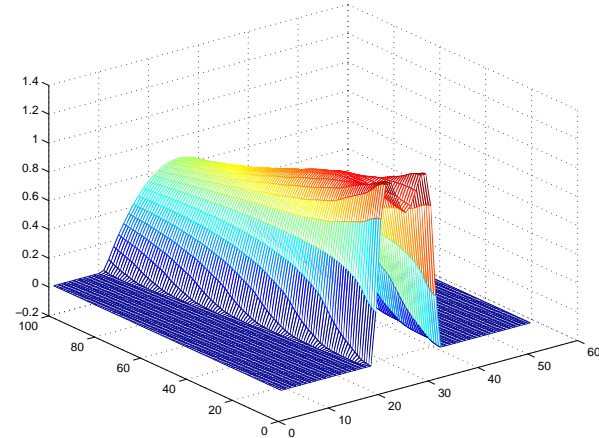
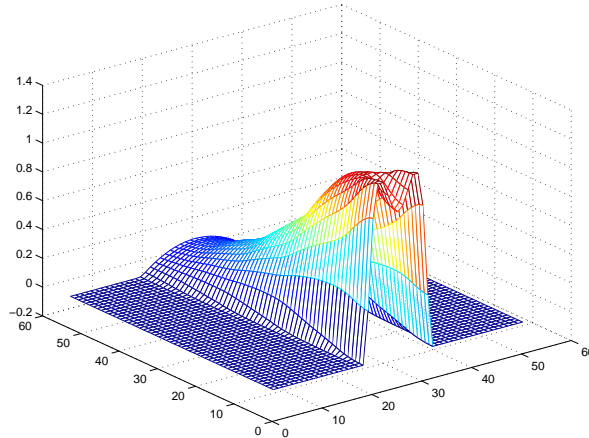
Moreover,

$$\frac{dD}{ds} = -R, \quad R \sim \lambda D.$$

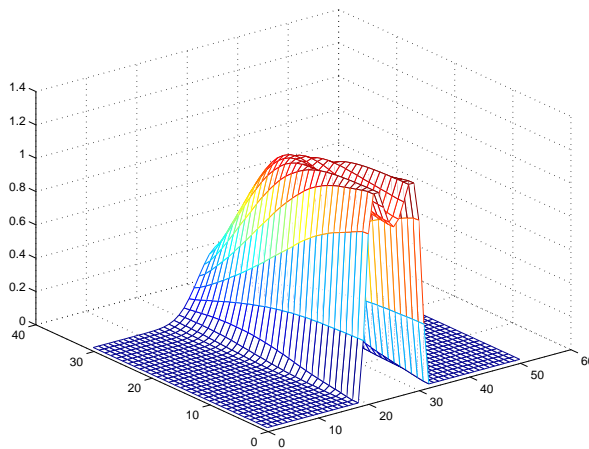
*We conclude exponential decay of D and E in **new time** s , which is potential in **real time** t .*

Asymptotics IV. Concavity

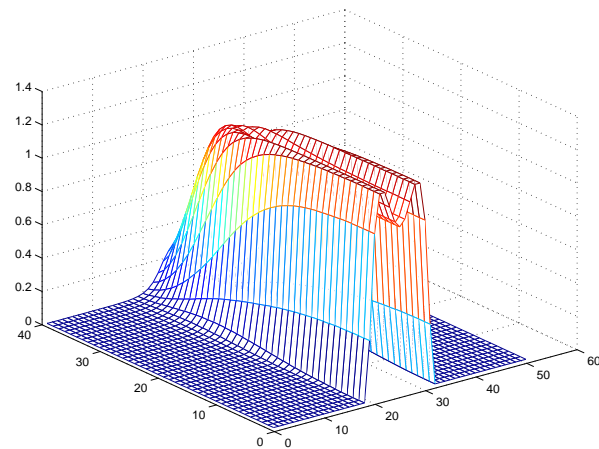
- The eventual concavity results of Lee and Vazquez



Eventual concavity for PME in 3D and in 1D



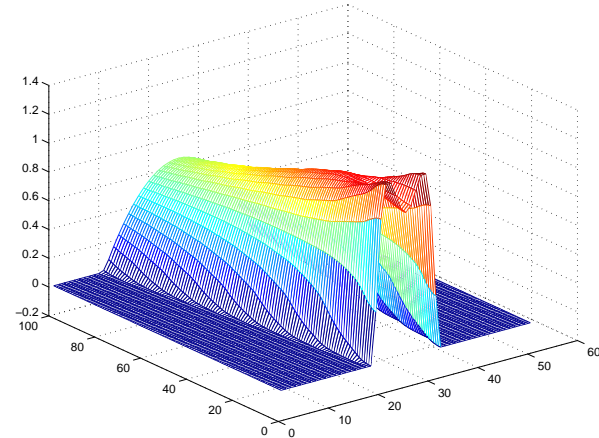
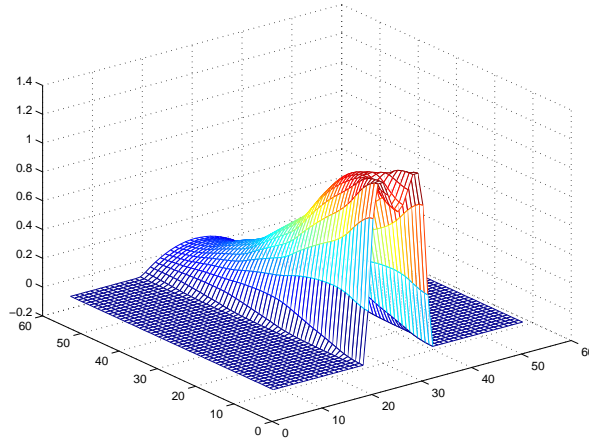
Eventual concavity for HE



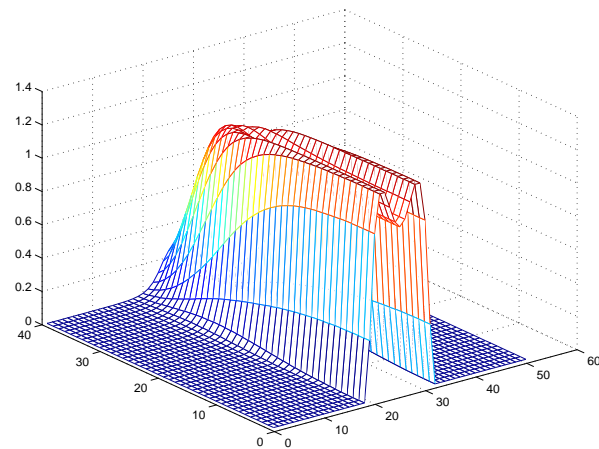
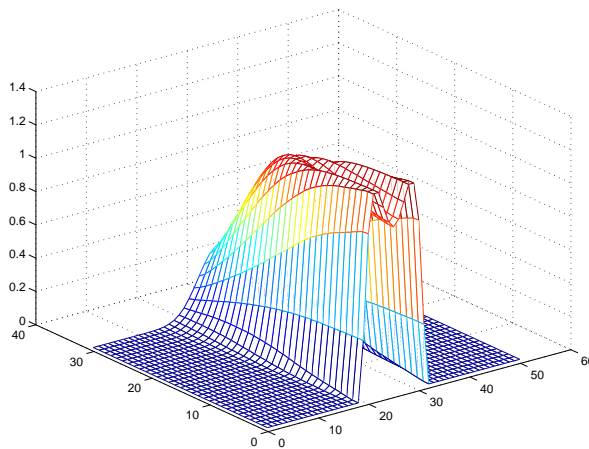
Eventual concavity for FDE

Asymptotics IV. Concavity

- The eventual concavity results of Lee and Vazquez



Eventual concavity for PME in 3D and in 1D

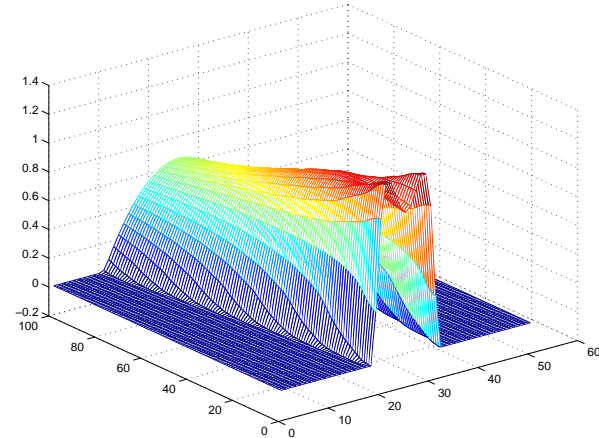
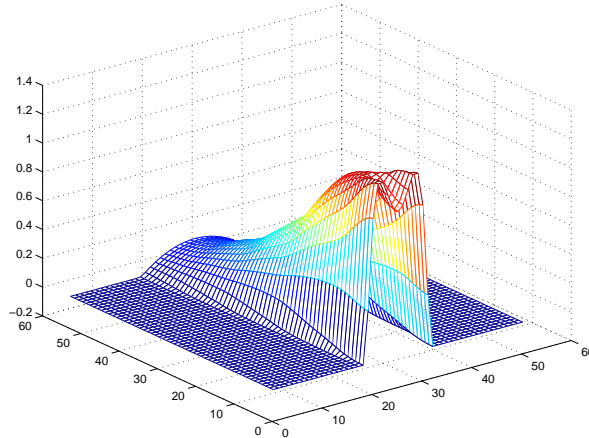


Eventual concavity for HE

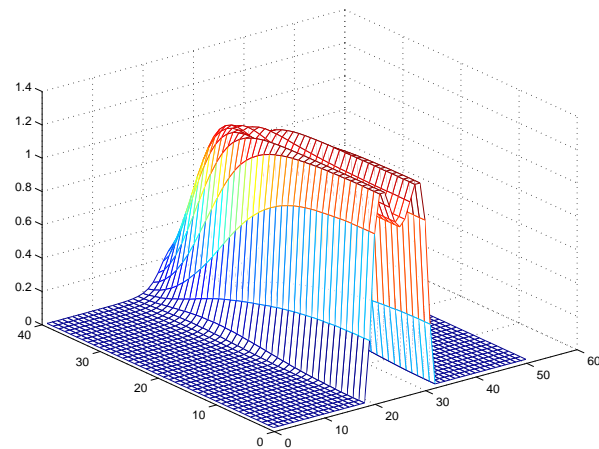
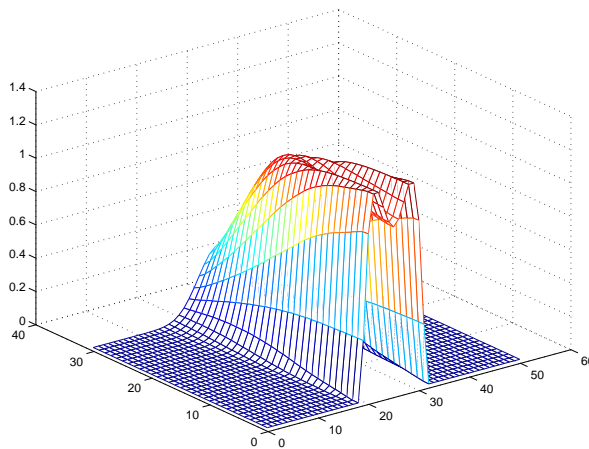
Eventual concavity for FDE

Asymptotics IV. Concavity

- The eventual concavity results of Lee and Vazquez



Eventual concavity for PME in 3D and in 1D



Eventual concavity for HE

Eventual concavity for FDE

References

About PME

- J. L. Vázquez, "The Porous Medium Equation. Mathematical Theory", Oxford Univ. Press, 2006 in press. approx. 600 pages

About estimates and scaling

References

About PME

- J. L. Vázquez, "The Porous Medium Equation. Mathematical Theory", Oxford Univ. Press, 2006 in press. approx. 600 pages

About estimates and scaling

- J. L. Vázquez, "Smoothing and Decay Estimates for Nonlinear Parabolic Equations of Porous Medium Type", Oxford Univ. Press, 2006, 234 pages.

About asymptotic behaviour. (*Following Lyapunov and Boltzmann*)

References

About PME

- J. L. Vázquez, "The Porous Medium Equation. Mathematical Theory", Oxford Univ. Press, 2006 in press. approx. 600 pages

About estimates and scaling

- J. L. Vázquez, "Smoothing and Decay Estimates for Nonlinear Parabolic Equations of Porous Medium Type", Oxford Univ. Press, 2006, 234 pages.

About asymptotic behaviour. (*Following Lyapunov and Boltzmann*)

- J. L. Vázquez. *Asymptotic behaviour for the Porous Medium Equation posed in the whole space.* Journal of Evolution Equations 3 (2003), 67–118.

References

About PME

- J. L. Vázquez, "The Porous Medium Equation. Mathematical Theory", Oxford Univ. Press, 2006 in press. approx. 600 pages

About estimates and scaling

- J. L. Vázquez, "Smoothing and Decay Estimates for Nonlinear Parabolic Equations of Porous Medium Type", Oxford Univ. Press, 2006, 234 pages.

About asymptotic behaviour. (*Following Lyapunov and Boltzmann*)

- J. L. Vázquez. *Asymptotic behaviour for the Porous Medium Equation posed in the whole space.* Journal of Evolution Equations 3 (2003), 67–118.

Probabilities. Wasserstein

● Definition of Wasserstein distance.

Let $\mathcal{P}(\mathbb{R}^n)$ be the set of probability measures. Let $p > 0$. μ_1, μ_2 probability measures.

$$(d_p(\mu_1, \mu_2))^p = \inf_{\pi \in \Pi} \int_{\mathbb{R}^n \times \mathbb{R}^n} |x - y|^p d\pi(x, y),$$

$\Pi = \Pi(\mu_1, \mu_2)$ is the set of all transport plans that move the measure μ_1 into μ_2 . This is a distance.

Technically, this means that π is a probability measure on the product space $\mathbb{R}^n \times \mathbb{R}^n$ that has marginals μ_1 and μ_2 . It can be proved that we may use transport functions $y = T(x)$ instead of transport plans (this is Monge's version of the transportation problem).

Probabilities. Wasserstein

- Definition of Wasserstein distance.

Let $\mathcal{P}(\mathbb{R}^n)$ be the set of probability measures. Let $p > 0$. μ_1, μ_2 probability measures.

$$(d_p(\mu_1, \mu_2))^p = \inf_{\pi \in \Pi} \int_{\mathbb{R}^n \times \mathbb{R}^n} |x - y|^p d\pi(x, y),$$

$\Pi = \Pi(\mu_1, \mu_2)$ is the set of all transport plans that move the measure μ_1 into μ_2 . This is a distance.

Technically, this means that π is a probability measure on the product space $\mathbb{R}^n \times \mathbb{R}^n$ that has marginals μ_1 and μ_2 . It can be proved that we may use transport functions $y = T(x)$ instead of transport plans (this is Monge's version of the transportation problem).

Wasserstein II

- In principle, for any two probability measures, the infimum may be infinite. But when $1 \leq p < \infty$, d_p defines a metric on the set \mathcal{P}_p of probability measures with finite p -moments, $\int |x|^p d\mu < \infty$. A convenient reference for this topic is Villani's book, "[Topics in Optimal Transportation](#)", 2003.

Wasserstein II

- In principle, for any two probability measures, the infimum may be infinite. But when $1 \leq p < \infty$, d_p defines a metric on the set \mathcal{P}_p of probability measures with finite p -moments, $\int |x|^p d\mu < \infty$. A convenient reference for this topic is Villani's book, "[Topics in Optimal Transportation](#)", 2003.
- The metric d_∞ plays an important role in controlling the location of free boundaries. Definition $d_\infty(\mu_1, \mu_2) = \inf_{\pi \in \Pi} d_{\pi, \infty}(\mu_1, \mu_2)$, with

$$d_{\pi, \infty}(\mu_1, \mu_2) = \sup\{|x - y| : (x, y) \in \text{support}(\pi)\}.$$

In other words, $d_{\pi, \infty}(\mu_1, \mu_2)$ is the maximal distance incurred by the transport plan π , i.e., the supremum of the distances $|x - y|$ such that $\pi(A) > 0$ on all small neighbourhoods A of (x, y) . We call this metric the [maximal transport distance](#).

Wasserstein III

- The contraction properties in $n = 1$

Theorem (Vazquez, 1983, 2004) *Let μ_1 and μ_2 be finite nonnegative Radon measures on the line and assume that $\mu_1(\mathbf{R}) = \mu_2(\mathbf{R})$ and $d_\infty(\mu_1, \mu_2)$ is finite. Let $u_i(x, t)$ the continuous weak solution of the PME with initial data μ_i . Then, for every $t_2 > t_1 > 0$*

$$d_\infty(u_1(\cdot, t_2), u_2(\cdot, t_2)) \leq d_\infty(u_1(\cdot, t_1), u_2(\cdot, t_1)) \leq d_\infty(\mu_1, \mu_2).$$

Theorem (Carrillo, 2004) *Contraction holds in d_p for all $p \in [1, \infty)$.*

Wasserstein III

- The contraction properties in $n = 1$

Theorem (Vazquez, 1983, 2004) *Let μ_1 and μ_2 be finite nonnegative Radon measures on the line and assume that $\mu_1(\mathbf{R}) = \mu_2(\mathbf{R})$ and $d_\infty(\mu_1, \mu_2)$ is finite. Let $u_i(x, t)$ the continuous weak solution of the PME with initial data μ_i . Then, for every $t_2 > t_1 > 0$*

$$d_\infty(u_1(\cdot, t_2), u_2(\cdot, t_2)) \leq d_\infty(u_1(\cdot, t_1), u_2(\cdot, t_1)) \leq d_\infty(\mu_1, \mu_2).$$

Theorem (Carrillo, 2004) *Contraction holds in d_p for all $p \in [1, \infty)$.*

- Contraction properties in $n > 1$

Theorem (McCann, 2003) *For the heat equation contraction holds for all p and $n \geq 1$. (Carrillo, McCann, Villani 2004) For the PME Contraction holds in d_2 for all $n \geq 1$.*

Wasserstein III

- The contraction properties in $n = 1$

Theorem (Vazquez, 1983, 2004) *Let μ_1 and μ_2 be finite nonnegative Radon measures on the line and assume that $\mu_1(\mathbf{R}) = \mu_2(\mathbf{R})$ and $d_\infty(\mu_1, \mu_2)$ is finite. Let $u_i(x, t)$ the continuous weak solution of the PME with initial data μ_i . Then, for every $t_2 > t_1 > 0$*

$$d_\infty(u_1(\cdot, t_2), u_2(\cdot, t_2)) \leq d_\infty(u_1(\cdot, t_1), u_2(\cdot, t_1)) \leq d_\infty(\mu_1, \mu_2).$$

Theorem (Carrillo, 2004) *Contraction holds in d_p for all $p \in [1, \infty)$.*

- Contraction properties in $n > 1$

Theorem (McCann, 2003) *For the heat equation contraction holds for all p and $n \geq 1$. (Carrillo, McCann, Villani 2004) For the PME Contraction holds in d_2 for all $n \geq 1$.*

Theorem (Vazquez, 2004) *For the PME, contraction does not hold in d_∞ for any $n > 1$. It does not in d_p for $p \geq p(n) > 2$.*

New fields

- Fast diffusion ($m < 1$)

$$u_t = \nabla \cdot (u^{m-1} \nabla u) = \nabla \cdot \left(\frac{\nabla u}{u^p} \right)$$

Geometrical applications: Yamabe flow, $m = (n - 2)/n$. Extinction.

see our book Smoothing

New fields

- Fast diffusion ($m < 1$)

$$u_t = \nabla \cdot (u^{m-1} \nabla u) = \nabla \cdot \left(\frac{\nabla u}{u^p} \right)$$

Geometrical applications: Yamabe flow, $m = (n - 2)/n$. Extinction.

see our book Smoothing

- Systems. The chemotaxis system leads to the formation of singularities in finite time through aggregation/concentration

Work by Herrero and Velazquez; Dolbeault and Perthame

New fields

- Fast diffusion ($m < 1$)

$$u_t = \nabla \cdot (u^{m-1} \nabla u) = \nabla \cdot \left(\frac{\nabla u}{u^p} \right)$$

Geometrical applications: Yamabe flow, $m = (n - 2)/n$. Extinction.

see our book Smoothing

- Systems. The chemotaxis system leads to the formation of singularities in finite time through aggregation/concentration

Work by Herrero and Velazquez; Dolbeault and Perthame

- General parabolic-hyperbolic equations and systems. Entropy solutions, renormalized solutions, shocks; limited diffusion

Work by J. Carrillo, Bénilan, Wittbold, ...

New fields

- Fast diffusion ($m < 1$)

$$u_t = \nabla \cdot (u^{m-1} \nabla u) = \nabla \cdot \left(\frac{\nabla u}{u^p} \right)$$

Geometrical applications: Yamabe flow, $m = (n - 2)/n$. Extinction.

see our book Smoothing

- Systems. The chemotaxis system leads to the formation of singularities in finite time through aggregation/concentration

Work by Herrero and Velazquez; Dolbeault and Perthame

- General parabolic-hyperbolic equations and systems. Entropy solutions, renormalized solutions, shocks; limited diffusion

Work by J. Carrillo, Bénilan, Wittbold, ...

- Nonlinear diffusion in image processing. Gradient dependent diffusion. Work on total variation models.

Andreu, Caselles, Mazón, ...